

NAG Toolbox for MATLAB

d03rz

1 Purpose

d03rz is designed to be used in conjunction with d03rb. It can be called from the user-supplied (sub)program **monitr** to obtain the number of grid points and their (x,y) co-ordinates on a solution grid.

2 Syntax

```
[npts, x, y, ifail] = d03rz(level, nlev, xmin, ymin, dxb, dyb, lgrid,
    istruc, lenxy)
```

3 Description

d03rz extracts the number of grid points and their (x,y) co-ordinates on a specific solution grid produced by d03rb. It must be called only from within the user-supplied (sub)program **monitr**. The parameters **nlev**, **xmin**, **ymin**, **dxb**, **dyb**, **lgrid** and **istruc** to **monitr** must be passed unchanged to d03rz.

4 References

None.

5 Parameters

5.1 Compulsory Input Parameters

1: **level** – int32 scalar

The grid level at which the co-ordinates are required.

Constraint: $1 \leq \text{level} \leq \text{nlev}$.

2: **nlev** – int32 scalar

3: **xmin** – double scalar

4: **ymin** – double scalar

5: **dxb** – double scalar

6: **dyb** – double scalar

7: **lgrid**(*) – int32 array

8: **istruc**(*) – int32 array

Note: the dimension of the array **lgrid** must be at least **nlev**.

The dimension of the array **istruc** must be at least **lgrid**(**nlev**) + $2 \times \text{nrows}$ + **npts** + 1 where **nrows** is stored in **istruc**(**lgrid**(**nlev**)) and is the number of rows in the grid at level **nlev**.

nlev, **xmin**, **ymin**, **dxb**, **dyb**, **lgrid** and **istruc** as supplied to user-supplied (sub)program **monitr** must be passed unchanged to d03rz.

9: **lenxy** – int32 scalar

Constraint: $\text{lenxy} \geq \text{npts}$.

5.2 Optional Input Parameters

None.

5.3 Input Parameters Omitted from the MATLAB Interface

None.

5.4 Output Parameters

1: **npts** – **int32 scalar**

The number of grid points in the grid level **level**.

2: **x(lenxy)** – **double array**

3: **y(lenxy)** – **double array**

x(i) and **y(i)** contain the (x,y) co-ordinates respectively of the i th grid point, for $i = 1, 2, \dots, \mathbf{npts}$.

4: **ifail** – **int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **level** < 1,
or **level** > **nlev**.

ifail = 2

The dimension of the arrays **x** and **y** is too small for the requested grid level, i.e., **lenxy** < **npts**.

7 Accuracy

Not applicable.

8 Further Comments

None.

9 Example

```
d03rb_boundary.m

function [res] = ...
    bndary(npts, npde, t, x, y, u, ut, ux, uy, nbnds, nbpts, llbnd,
    ilbnd, lbnd, res)

    eps = 1e-3;

    for k = llbnd(1):nbpts
        i = lbnd(k);
        a = (-4.0d0*x(i)+4.0d0*y(i)-t)/(32.0d0*eps);
        if (a <= 0.0d0)
            res(i,1) = u(i,1) - (0.75d0-0.25d0/(1.0d0+exp(a)));
            res(i,2) = u(i,2) - (0.75d0+0.25d0/(1.0d0+exp(a)));
        else
            res(i,1) = u(i,1) - (0.75d0-0.25d0*exp(-a)/(exp(-
a)+1.0d0));
            res(i,2) = u(i,2) - (0.75d0+0.25d0*exp(-a)/(exp(-
a)+1.0d0));
        end
    end
```



```
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8),
int32(9),
int32(10),
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8),
int32(9),
int32(10),
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8),
int32(9),
int32(10),
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8),
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8),
int32(0),
int32(1),
int32(2),
int32(3),
int32(4),
int32(5),
int32(6),
int32(7),
int32(8)];
```

```
ilbndd = [int32(1),
int32(2),
int32(3),
int32(4),
int32(1),
int32(4),
int32(1),
int32(2),
int32(3),
int32(3),
```

```

        int32(4),
        int32(3),
        int32(4),
        int32(1),
        int32(2),
        int32(12),
        int32(23),
        int32(34),
        int32(41),
        int32(14),
        int32(41),
        int32(12),
        int32(23),
        int32(34),
        int32(41),
        int32(43),
        int32(14),
        int32(21),
        int32(32)];

irowd = [int32(0),
        int32(1),
        int32(2),
        int32(3),
        int32(4),
        int32(5),
        int32(6),
        int32(7),
        int32(8),
        int32(9),
        int32(10)];

lbndd = [int32(2),
        int32(4),
        int32(15),
        int32(26),
        int32(37),
        int32(46),
        int32(57),
        int32(68),
        int32(79),
        int32(88),
        int32(98),
        int32(99),
        int32(100),
        int32(101),
        int32(102),
        int32(103),
        int32(104),
        int32(96),
        int32(86),
        int32(85),
        int32(84),
        int32(83),
        int32(82),
        int32(70),
        int32(59),
        int32(48),
        int32(39),
        int32(28),
        int32(17),
        int32(6),
        int32(8),
        int32(9),
        int32(10),
        int32(11),
        int32(12),
        int32(13),
        int32(18),
        int32(29),

```

```
int32(40),
int32(49),
int32(60),
int32(72),
int32(73),
int32(74),
int32(75),
int32(76),
int32(77),
int32(67),
int32(56),
int32(45),
int32(36),
int32(25),
int32(33),
int32(32),
int32(42),
int32(52),
int32(53),
int32(43),
int32(1),
int32(97),
int32(105),
int32(87),
int32(81),
int32(3),
int32(7),
int32(71),
int32(78),
int32(14),
int32(31),
int32(51),
int32(54),
int32(34)];

llbndd = [int32(1),
int32(2),
int32(11),
int32(18),
int32(19),
int32(24),
int32(31),
int32(37),
int32(42),
int32(48),
int32(53),
int32(55),
int32(56),
int32(58),
int32(59),
int32(60),
int32(61),
int32(62),
int32(63),
int32(64),
int32(65),
int32(66),
int32(67),
int32(68),
int32(69),
int32(70),
int32(71),
int32(72)];

lrowd = [int32(1),
int32(4),
int32(15),
int32(26),
int32(37),
int32(46),
```

```

        int32(57),
        int32(68),
        int32(79),
        int32(88),
        int32(97)];

    nx = int32(11);
    ny = int32(11);

% check maxpts against rough estimate of npts
    if (maxpts < nx*ny)
        ierr = -1;
        return;
    end

    xmin = 0.0d0;
    ymin = 0.0d0;
    xmax = 1.0d0;
    ymax = 1.0d0;

    for i = 1:nrows
        lrow(i) = lrowd(i);
        irow(i) = irowd(i);
    end

    for i = 1:nbnds
        llbnd(i) = llbndd(i);
        ilbnd(i) = ilbndd(i);
    end

    for i = 1:nbpts
        lbnd(i) = lbndd(i);
    end

    for i = 1:npts
        icol(i) = icold(i);
    end

```

d03rb_pdedef.m

```

function [res] = pdedef(npts, npde, t, x, y, u, ut, ux, uy, uxx, uxy,
    uyy)
    res = zeros(npts, npde);

    eps = 1e-3;
    for i = 1:npts
        res(i,1) = ut(i,1) - (-u(i,1)*ux(i,1) -
    u(i,2)*uy(i,1) + eps*(uxx(i,1) + uyy(i,1)));
        res(i,2) = ut(i,2) - (-u(i,1)*ux(i,2) -
    u(i,2)*uy(i,2) + eps*(uxx(i,2) + uyy(i,2)));
    end

```

d03rb_pdeiv.m

```

function [u] = pdeiv(npts, npde, t, x, y)
    u = zeros(npts, npde);

    eps = 1e-3;

    for i = 1:npts
        a = (-4.0d0*x(i) + 4.0d0*y(i) - t)/(32.0d0*eps);
        if (a <= 0.0d0)
            u(i,1) = 0.75d0 - 0.25d0/(1.0d0+exp(a));
            u(i,2) = 0.75d0 + 0.25d0/(1.0d0+exp(a));
        else
            u(i,1) = 0.75d0 - 0.25d0*exp(-a)/(exp(-a)+1.0d0);
            u(i,2) = 0.75d0 + 0.25d0*exp(-a)/(exp(-a)+1.0d0);
        end
    end

```

```

    end
end

```

```
d03rz_monitr.m
```

```

function [ierr] = ...
    monitr(npde, t, dt, dtnew, tlast, nlev, xmin, ymin, dx, dy,
    lgrid, ...
        istruc, lsol, sol, ierr)

    lenxy=int32(2500);

    global iout;

    if (tlast && iout == 2)
        for level = 1:nlev
            ipsol = lsol(level);

            % Get grid information
            [npts, x, y, ifail] = ...
                d03rz(level, nlev, xmin, ymin, dx, dy, lgrid, istruc, lenxy);
            if (ifail ~= 0)
                ierr = 1;
            elseif (level == 1)
                % Get exact solution
                [uex] = d03rb_pdeiv(npts, npde, t, x, y);

                fprintf('\n Solution at every 2nd grid point in level 1 at time
%8.4f\n', t);
                fprintf('
                x                y                approx u                exact u
approx v                exact v\n');
                for ipt = 1:2:npts
                    fprintf('%11.4E %11.4e %11.4e %11.4e %11.4e %11.4e\n',
x(ipt), ...
                    y(ipt), sol(ipsol+ipt), uex(ipt,1), sol(ipsol+npts+ipt),
uex(ipt,2));
                    end
                    fprintf('\n');
                end
            end
        end
    end
end

```

```

ts = 0;
twant = [0.25; 1];
dt = [0.001;
    1e-07;
    0];
tols = 0.1;
tolt = 0.05;
opti = [int32(5);
    int32(0);
    int32(0);
    int32(0)];
optr = [1, 1;
    1, 1;
    1, 1];
rwk = zeros(426000, 1);
iwk = zeros(117037, 1, 'int32');
lenlwk = int32(6000);
itrace = int32(0);
ind = int32(0);
global iout;
for iout = 1:2
    tout = twant(iout);
    [ts, dt, rwk, iwk, ind, ifail] = ...
        d03rb(ts, tout, dt, tols, tolt, 'd03rb_inidom', 'd03rb_pdedef', ...

```

```

    'd03rb_bndary', 'd03rb_pdeiv', 'd03rz_monitr', opti, optr, ...
    rwk, iwk, lenlwk, itrace, ind);
fprintf('\nStatistics\n');
fprintf('Time = %8.4f\n', ts);
fprintf('Total number of accepted timesteps = %d\n', iwk(1));
fprintf('Total number of rejected timesteps = %d\n', iwk(2));
fprintf('\n          T o t a l n u m b e r o f      \n');
fprintf('          Residual Jacobian   Newton   Lin sys\n');
fprintf('          evals      evals      iters      iters\n');
fprintf(' At level \n');
maxlev = opti(1);
for j = 1:maxlev
    if (iwk(j+2) ~= 0)
        fprintf('%6d %10d %10d %10d %10d\n', j, iwk(j+2), iwk(j+2+maxlev),
...
                                iwk(j+2+2*maxlev), iwk(j+2+3*maxlev) );
    end
end
fprintf('\n          M a x i m u m   n u m b e r   o f\n');
fprintf('          Newton iters      Lin sys iters \n');
fprintf(' At level \n');
for j = 1:maxlev
    if (iwk(j+2) ~= 0)
        fprintf('%6d%14d%14d\n', j, iwk(j+2+4*maxlev), iwk(j+2+5*maxlev) );
    end
end
end
end

```

Statistics

Time = 0.2500

Total number of accepted timesteps = 14

Total number of rejected timesteps = 0

	T o t a l n u m b e r o f			
	Residual	Jacobian	Newton	Lin sys
	evals	evals	iters	iters
At level				
1	196	14	28	14
2	196	14	28	22
3	196	14	28	25
4	196	14	28	31
5	141	10	21	29

	M a x i m u m n u m b e r o f	
	Newton iters	Lin sys iters
At level		
1	2	1
2	2	1
3	2	1
4	2	2
5	3	2

Solution at every 2nd grid point in level 1 at time 1.0000

x	y	approx u	exact u	approx v	exact v
0.0000E+00	0.0000e+00	5.0000e-01	5.0000e-01	1.0000e-00	1.0000e-00
2.0000E-01	0.0000e+00	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
1.0000E-01	1.0000e-01	5.0022e-01	5.0000e-01	9.9978e-01	1.0000e-00
3.0000E-01	1.0000e-01	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
5.0000E-01	1.0000e-01	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
7.0000E-01	1.0000e-01	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
9.0000E-01	1.0000e-01	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
0.0000E+00	2.0000e-01	5.0048e-01	5.0048e-01	9.9952e-01	9.9952e-01
2.0000E-01	2.0000e-01	5.0000e-01	5.0000e-01	1.0000e-00	1.0000e-00
4.0000E-01	2.0000e-01	5.0011e-01	5.0000e-01	9.9989e-01	1.0000e+00
6.0000E-01	2.0000e-01	4.9994e-01	5.0000e-01	1.0001e+00	1.0000e+00
8.0000E-01	2.0000e-01	4.9999e-01	5.0000e-01	1.0000e+00	1.0000e+00
1.0000E+00	2.0000e-01	5.0000e-01	5.0000e-01	1.0000e+00	1.0000e+00
1.0000E-01	3.0000e-01	4.9997e-01	5.0048e-01	1.0000e+00	9.9952e-01
3.0000E-01	3.0000e-01	5.0000e-01	5.0000e-01	1.0000e-00	1.0000e-00

```

5.0000E-01  3.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
7.0000E-01  3.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
9.0000E-01  3.0000e-01  5.0003e-01  5.0000e-01  9.9997e-01  1.0000e+00
0.0000E+00  4.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
2.0000E-01  4.0000e-01  5.0048e-01  5.0048e-01  9.9952e-01  9.9952e-01
4.0000E-01  4.0000e-01  5.0018e-01  5.0000e-01  9.9982e-01  1.0000e-00
8.0000E-01  4.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
1.0000E+00  4.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
1.0000E-01  5.0000e-01  7.4998e-01  7.5000e-01  7.5002e-01  7.5000e-01
3.0000E-01  5.0000e-01  5.0048e-01  5.0048e-01  9.9952e-01  9.9952e-01
5.0000E-01  5.0000e-01  5.0000e-01  5.0000e-01  1.0000e-00  1.0000e-00
7.0000E-01  5.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
9.0000E-01  5.0000e-01  5.0005e-01  5.0000e-01  9.9995e-01  1.0000e+00
0.0000E+00  6.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
2.0000E-01  6.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
4.0000E-01  6.0000e-01  4.9998e-01  5.0048e-01  1.0000e+00  9.9952e-01
6.0000E-01  6.0000e-01  4.9991e-01  5.0000e-01  1.0001e+00  1.0000e-00
8.0000E-01  6.0000e-01  4.9983e-01  5.0000e-01  1.0002e+00  1.0000e+00
1.0000E+00  6.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
1.0000E-01  7.0000e-01  7.5002e-01  7.5000e-01  7.4998e-01  7.5000e-01
3.0000E-01  7.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
5.0000E-01  7.0000e-01  5.0048e-01  5.0048e-01  9.9952e-01  9.9952e-01
7.0000E-01  7.0000e-01  5.0000e-01  5.0000e-01  1.0000e-00  1.0000e-00
9.0000E-01  7.0000e-01  5.0000e-01  5.0000e-01  1.0000e+00  1.0000e+00
0.0000E+00  8.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
2.0000E-01  8.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
4.0000E-01  8.0000e-01  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
6.0000E-01  8.0000e-01  5.0048e-01  5.0048e-01  9.9952e-01  9.9952e-01
8.0000E-01  8.0000e-01  5.0000e-01  5.0000e-01  1.0000e-00  1.0000e-00
1.0000E-01  9.0000e-01  7.5001e-01  7.5000e-01  7.4999e-01  7.5000e-01
3.0000E-01  9.0000e-01  7.5002e-01  7.5000e-01  7.4998e-01  7.5000e-01
5.0000E-01  9.0000e-01  7.5002e-01  7.5000e-01  7.4998e-01  7.5000e-01
7.0000E-01  9.0000e-01  4.9994e-01  5.0048e-01  1.0001e+00  9.9952e-01
0.0000E+00  1.0000e+00  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
2.0000E-01  1.0000e+00  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
4.0000E-01  1.0000e+00  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
6.0000E-01  1.0000e+00  7.5000e-01  7.5000e-01  7.5000e-01  7.5000e-01
8.0000E-01  1.0000e+00  5.0048e-01  5.0048e-01  9.9952e-01  9.9952e-01

```

Statistics

Time = 1.0000

Total number of accepted timesteps = 45

Total number of rejected timesteps = 0

	T o t a l n u m b e r o f			
At level	Residual evals	Jacobian evals	Newton iters	Lin sys iters
1	630	45	90	45
2	630	45	90	78
3	630	45	90	87
4	630	45	90	124
5	575	41	83	122

	M a x i m u m n u m b e r o f	
At level	Newton iters	Lin sys iters
1	2	1
2	2	1
3	2	1
4	2	2
5	3	2